WORKING PROCEDURE	WP 033
Title	Page Number
PNGV Dynamometer Load Cell Calibration	1 of 12
Originator	Supersedes
Stephen Pfeiffer	N/A
Responsible Organization	Computer Program
Clean Car/PNGV Group	PowerTek System
Type of Test Report	Data Form Number
Cal Plot for tqDYNO_CASE and Calibration Summary	N/A
Report Distribution	Implementation Date
Dynamometer Calibrations Records cabinet.	04-30-2000

Implementation Approval

Original Test Procedure Authorized by EPCN #266 on 04-30-2000

Revision Description Note:

Specific brand names in this procedure are for reference only and are not an endorsement of that product.

Table of Contents

1.	Purpose
2.	Test Procedure
3.	Acceptance Criteria
	<u>Figures</u>
	Figure 1 Disengaged Driveshaft
	Figure 2 Oil Flow Gauge
	Figure 3 Calibration Arm Attachment
	Figure 4 Selecting tqDYNO_CASE
	Figure 5 Signal Display 5
	Figure 6 Setpoint Editor
	Figure 7 Direction Arrow
	Figure 8 Cal Plot for tqDYNO_CASE 10
	Figure 9 Review History Screen

1. Purpose

The purpose of this procedure is to document the steps required to perform the dynamometer load cell calibration for PNGV cells.

2. Test Procedure

- Press E Stop, the mechanical red emergency button.
- Ensure that the driveshaft is disconnected. If it is in place, remove the four bolts holding the cover in place, and then remove the cover plate.

In some cells, you can only remove 2 bolts, and then the cover can be raised while it remains attached on the one side.

Remove the 4 bolts connecting the driveshaft mounting flange to the dynamometer. See Figure 1.

Use a pry-bar to disengage the driveshaft from its seat, so that it is not touching the dynamometer shaft.

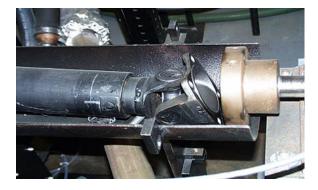


Figure 1
Disengaged Driveshaft

If the PowerTek VX-In Engine controller computers and monitor are not turned on, follow WP 031 "PNGV Start VX-In" for the startup procedure.

On the cell's Controller monitor, open the "Displays" toolbar, select "Softpanel", and then select "EPA_BTN_BREAKIN' from the scroll menu.

Turn on the dynamometer by clicking the "Enable Drive" button under "Log #1".

Once the dyno is turned on, visually verify that the fans on the dyno are operating. Inspect the two oil flow gauges on opposite sides of the dyno to verify that oil is dripping at the rate of 60 ± 10 drops per minute or approximately one drop per second.



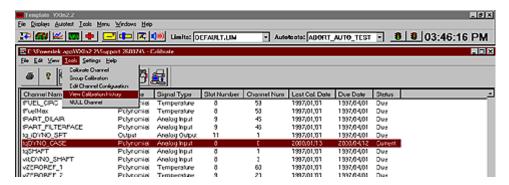
Figure 2 Oil Flow Gauge

In the cell, attach the pair of calibration arms to the dyno. Each dynamometer has its own set of arms identified by the matching ID number found on the arm and on the arm attachment. See Figure 3. The ID number also appears on the cover of the metal storage container of the weights. Correct connection of each arm is evident by the completion of the small circle between the set of identical numbers on the arm and the arm attachment.



Figure 3
Calibration Arm Attachment

- On the controller monitor, open the "Displays" toolbar and select "Special" then select "Calibrate".
- On the "Calibrate" screen, scroll up or down the "Channel Names" until "tqDYNO_CASE" appears. See Figure 4. Double click on "tqDYNO_CASE".



Selecting tqDYNO_CASE

- "Operator ID" prompt will appear. Enter the operator ID and press "OK". Verify that the channel name is "tqDYNO_CASE".
- The "Signal Display" screeen will appear. See Figure 5. Next to "Polynomial Order" select the field area by doubleclicking on it and type in '3'.

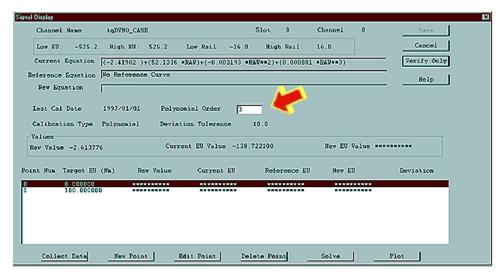


Figure 5
Signal Display

- In the bottom panel of the "Signal Display" screen, verify that "Target EU" 0.000000 is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".
- If the Target EU 0.000000 is not listed on the Signal Display screen, click on "New Point" button. The "Setpoint Editor" window for Target EU will appear. See Figure 6.

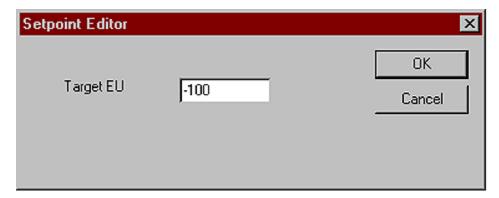


Figure 6 Setpoint Editor

Select the entry window for Target EU by clicking the mouse on it. Then type in "0.00" and click on "OK". When the "Signal Display" screen appears, highlight Target EU "0.000000" and then click on the "Collect Data" button. A raw value will appear next to "Target EU".

In preparation for adding weights on the arms, the determination of positive and negative changes relies on the direction of the arrow point on the drive shaft mount. The arrow points to the positive side. See Figure 7.



Figure 7
Direction Arrow



- In the cell, attach the hang basket to the negative side arm of the drive shaft. The basket represents 100 Newton-meters. Once attached, tap on it to remove hysteresis.
- In the bottom panel of the "Signal Display" screen, verify that Target EU "-100" is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".
- If the Target EU -100 is not listed on the Signal Display screen, click on "New Point" button. The Setpoint Editor for Target EU will appear.

Select the entry window for Target EU by clicking the mouse on it. Then type in "-100" and click on "OK".

When the "Signal Display" screen appears, highlight Target EU "-100" and then click on the "Collect Data" button. A raw value will appear next to the "Target EU".

- In the cell add a second weight which represents 100 Newton-meters to the hang basket for a total of -200 Newton-meters. Once attached, tap on it to remove hysteresis.
- In the bottom panel of the "Signal Display" screen, verify that Target EU '-200' appears. If it is listed, highlight it and click on the "Collect Data" button.

If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".

If the Target EU -200 is not listed on the "Signal Display" screen, click on "New Point" button. The "Setpoint Editor" window for Target EU will appear.

Select the entry window for Target EU by clicking the mouse on it. Then type in "-200" and click on "OK".

When the "Signal Display" screen appears, highlight Target EU "-200" and then click on the "Collect Data" button. A raw value will appear next to "Target EU".

- In the cell add a third weight which represents 100 Newton-meters to the hang basket for a total of -300 Newton-meters. Once attached, tap on it to remove hysteresis.
- In the bottom panel of the "Signal Display" screen, verify that "Target EU" -300 is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".
- If the "Target EU" -300 is not listed on the "Signal Display" screen, click on the "New Point" button. The "Setpoint Editor" window for "Target EU" will appear.

Select the entry window for Target EU by clicking the mouse on it. Then type in "-300" and click on "OK".

When the "Signal Display" screen appears, highlight Target EU "-300" and then click on the "Collect Data" button. A raw value will appear nest to the "Target EU".

- In the cell add two more weights that represent 100 Newton-meters each and a weight that represents 50 Newton-meters to the hang basket for a total of -550 Newton-meters. Once attached, tap on it to remove hysteresis.
- In the bottom panel of the "Signal Display" screen, verify that "Target EU" -550 is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".
- If the Target EU -550 is not listed on the "Signal Display" screen, click on "New Point" button. The "Setpoint Editor" window for Target EU will appear.

Select the entry window for Target EU by clicking the mouse on it. Then type in "-550" and click on "OK".

When the "Signal Display" screen appears, highlight Target EU "-550" and then click on the "Collect Data" button. A raw value will appear next to "Target EU".

Begin removing the weights, one by one, in the order they were added and check the raw value with each removal. Each time the weight is detached, tap on the basket to remove hysteresis.

On the screen, check the raw value with each removal. The raw value should match the current EU value for each weight within \pm 1% of the total value. Once all the weights are removed from the negative side, repeat the calibration process on the positive side.

- In the cell, attach the hang basket to the negative side arm of the drive shaft. The basket represents 100 Newton-meters. Once attached, tap on it to remove hysteresis.
- In the bottom panel of the "Signal Display" screen, verify that "Target EU" 100 is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".
- If the Target EU 100 is not listed on the "Signal Display" screen, click on "New Point" button. The "Setpoint Editor" window for Target EU will appear.

Select the entry window for Target EU by clicking the mouse on it. Then type in "100" and click on "OK".

When the "Signal Display" screen appears, highlight Target EU "100" and then click on the "Collect Data" button. A raw value will appear next to "Target EU".

- In the cell add a second weight which represents 100 Newton-meters to the hang basket for a total of 200 Newton-meters. Once attached, tap on it to remove hysteresis.
- In the bottom panel of the "Signal Display" screen, verify that "Target EU" 200 is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".

- If the Target EU 200 is not listed on the "Signal Display" screen, click on "New Point" button. The "Setpoint Editor" window for Target EU will appear.
 - Select the entry window for Target EU by clicking the mouse on it. Then type in "200" and click on "OK".
 - When the "Signal Display" screen appears, highlight Target EU "200" and then click on the "Collect Data" button. A raw value will appear next to "Target EU".
- In the cell add a third weight which represents 100 Newton-meters to the hang basket for a total of 300 Newton-meters. Once attached, tap on it to remove hysteresis.
- In the bottom panel of the "Signal Display" screen, verify that "Target EU" 300 is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".
- If the Target EU 300 is not listed on the "Signal Display" screen, click on "New Point" button. The "Setpoint Editor" window for Target EU will appear.
 - Select the entry window for Target EU by clicking the mouse on it. Then type in "300" and click on "OK".
 - When the "Signal Display" screen appears, highlight Target EU "300" and then click on the "Collect Data" button. A raw value will appear next to "Target EU".
- In the cell add a fourth weight which represents 100 Newton-meters to the hang basket for a total of 400 Newton-meters. Once attached, tap on it to remove hysteresis.
- In the bottom panel of the "Signal Display" screen, verify that "Target EU" 400 is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".
- If the Target EU 400 is not listed on the "Signal Display" screen, click on "New Point" button. The "Setpoint Editor" window for Target EU will appear.
 - Select the entry window for Target EU by clicking the mouse on it. Then type in "400" and click on "OK". When the "Signal Display" screen appears, highlight Target EU "400" and then click on the "Collect Data" button. A raw value will appear next to "Target EU".
- n the cell add another weight that represents 100 Newton-meters and a weight that represents 50 Newton-meters to the hang basket for a total of 550 Newton-meters. Once attached, tap on it to remove hysteresis.
- In the bottom panel of the "Signal Display" screen, verify hat "Target EU" 550 is listed. If it is listed, highlight it and click on the "Collect Data" button. A raw value will appear next to "Target EU".

- If the Target EU 550 is not listed on the "Signal Display" screen, click on "New Point" button. The "Setpoint Editor" window for Target EU will appear.
 - Select the entry window for Target EU by clicking the mouse on it. Then type in "550" and click on "OK".
 - When the "Signal Display" screen appears, highlight Target EU "550" and then click on the "Collect Data" button. A raw value will appear next to "Target EU".
- Begin removing the weights, one by one, in the order they were added and check the raw value with each removal. Each time the weight is detached, tap on the basket to remove hysteresis.
 - On the screen, check the raw value with each removal. The raw value should match the current EU value for each weight within \pm 1% of the total value.
- Once all the positive weights are removed, click on the "Solve" button. Verify that you have new EU numbers in the panel.
- 145 Click on the "Plot" button.
- The "Cal Plot for tqDYNO_CASE" appears. See Figure 8. Verify that the plot forms a straight line.

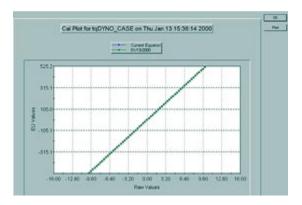


Figure 8
Cal Plot for tqDYNO_CASE

- In the upper right corner of the "CalPlot" display, press the "Print" button.
- 148 Click on the "OK" button of the Cal Plot display to return to the Signal Display screen.
- 149 Click on "Save" button of the Signal Display to return to the "Calibrate" screen.
- On the "Calibrate" screen, select "Tools" menu, and from the menu select "View Calibration History".

Ensure that "tqDYNO_CASE" appears on the "Review History" screen in the "Channel Name" box. See Figure 9.

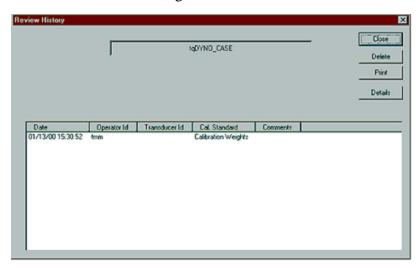


Figure 9 Review History Screen

- From the list in the bottom display, highlight the calibration that was just performed.
- 153 Click on the "Print" button in the upper right hand corner.
- 154 Click "OK" when the "Print" screen appears.
- A calibration report will be printed. On the "Review Hisory" screen, click "Close".
- On the "Calibrate" screen, click on the "File" menu and select "EXIT".
- In the cell, remove the calibration arms for the dyno, and return them with the bolts to their storage box.
- Re-attach driveshaft to dynamometer by loosely threading the bolts to the mounting flange.
- Tighten one bolt with a torque wrench to 65 ft.-lbs. Use a prybar to rotate the driveshaft.
- Tighten with a torque wrench the bolt opposite the first one to 65 ft-lbs. Use a prybar to rotate the driveshaft.
- Use the torque wrench to tighten the third bolt to 65 ft-lbs. Use a prybar to rotate the driveshaft.

W W 7 W			
WI	' (1.5	3

PNGV Dynamometer Load Cell Calibration

Page 12 of 12

- Tighten the remaining bolt with the torque wrench to 65 ft-lbs.
- Repeat the procedure used in Steps 159-161 to tighten the four bolts with a torque wrench to 75 ft-lbs.
- Replace the driveshaft cover by securing either the removed four or the removed two bolts back to it.
- Shut down the computer by following the steps in WP 032 "PNGV Stop VX-In".
- Staple the "Cal Plot for tqDYNO_CASE" and "Calibration Summary" printouts together and place them in the "Dynamometer Calibrations Records" cabinet.

3. Acceptance Criteria

- 3.1 The oil in the two oil flow gauges must be dripping at the 60 ± 10 drops per minute rate.
- 3.2 The raw value must match the current EU value for each weight within \pm 1% of the total value.
- 3.3 The Cal Plot data visually forms a straight line.
- 3.4 The Cal Plot for tqDYNO_CASE" and "Calibration Summary" printouts are filed in the "Dynamometer Calibrations Records" cabinet.
- 3.5 The four bolts to the mounting flange are tightened to 75 ft.-lbs.